

# Andreas Ziegler

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[in andreas-ziegler](#)



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## Personal details

Date of birth 25.03.1988

Nationality Swiss

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## Education

09.2014–04.2018 **Zurich, ETH**, MSc ETH in EEIT

Courses taken:

- Computer Vision
- Machine Learning, Data Mining, Signal and Information Processing
- Recursive Estimation, Dynamic Programming & Optimal Control
- Distributed Control
- Robot Dynamics
- How to write fast numerical code

Master Thesis: A Representation for Exploration that is Robust to State Estimate Drift

- Topics: Robotics, Exploration, Localization, Mapping
- Examiner: Prof. Dr. Roland Siegwart and Prof. Dr. Davide Scaramuzza

Semester Project 2: Map Fusion for Collaborative UAV SLAM

- Topics: Computer Vision, Robotics, Optimization
- Examiner: Prof. Dr. Roland Siegwart and Prof. Dr. Margarita Chli

Semester Project 1: Robust object tracking in 3D by fusing ultra-wideband and vision

- Topics: Computer Vision, Sensor Fusion, Robotics
- Examiner: Prof. Dr. Luc Van Gool and Prof. Dr. Otmar Hilliges

09.2009–09.2013 **Rapperswil, Switzerland**, *University of Applied Science Eastern Switzerland (HSR)*, BSc FHO in Electrical Engineering

Courses taken:

- Digital Signal processing
- Digital Image processing
- Embedded Systems / Embedded Software Engineering
- Mobile Communication

Semester thesis: Zuverlässige Sturzdetektion mit 9DOF-Schuhen

- Topic: Digital Signal processing
- Examiner: Prof. Dr. Guido Schuster

Bachelor thesis: Mobile datalogger for recording decentral captured dynamic motor vehicle data

- Topic: Embedded Software Engineering
- Examiner: Prof. Reto Bonderer

09.2011–08.2012 **Shanghai, China**, *Shanghai Jiao Tong University*, Exchange student, *School of Electric Information and Electrical Engineering*

Courses taken: Chinese language course, Electrical engineering and Computer Science courses

08.2004–08.2008 **Uster, Switzerland**, *Bildungszentrum Uster*, Technische Berufsmatura

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## Independent Coursework

- edX DT-01x: Self-Driving Cars with Duckietown by ETHx on edX. Specialization Certificate earned on August 15, 2021
- Coursera Deep Learning, a 5-course specialization by deeplearning.ai on Coursera. Specialization Certificate earned on March 16, 2018
- edX Autonomous Mobile Robots by ETHx on edX. Certificate earned on April 17, 2014

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## Work experience

- 06.2021–present **Tübingen, Germany**, *University of Tübingen, PhD candidate*, 100%  
Working on Event-based computer vision for fast robot control in collaboration with Sony AI Zürich
- 09.2018–05.2021 **Zwingen, Switzerland**, *MT Robot AG, Robotics Engineer*, 100%  
Accomplished tasks:
  - Development of a computer vision based safety field intrusion detection system
  - Improvement of a multi robot collision avoidance system
  - Development and maintenance of software for automated guided vehicle (AGVs), including topics such as multi sensor fusion, mapping, path planning, (multi robot) obstacle avoidance, etc.
  - Deputy Scrum MasterTechnologies used: C++, Python, ROS1/2, DDS, OpenCV, CMake, git, Atlassian tools
- 06.2018–09.2018 **Zurich, Switzerland**, *University of Zurich, Robotics and Perception Group, Research Assistant*, 100%  
Accomplished tasks:
  - Research on mapping for exploration.Technologies used: Python, git, L<sup>A</sup>T<sub>E</sub>X
- 04.2018–06.2018 **Zurich, Switzerland**, *Disney Research Zurich, Research Associate Intern*, 100%  
Accomplished tasks:
  - Worked on localization and sensor fusion for a UAVTechnologies used: C++, Python, ROS, Ceres, CMake, git
- 03.2017–08.2017 **Lausanne, Switzerland**, *Pix4D SA, Computer Vision & Robotics Research Intern*, 100%  
Accomplished tasks:
  - Worked on indoor navigation for UAVs
  - Implementation of a filtering method for a robust target detection
  - Participation on an indoor mapping project with an industrial partner
  - Investigation of barcode localization and detection algorithms for automatic inventory
  - Participation on a development of a target detection library for radiometric corrections
  - Worked on various computer vision applications (Barcode localization/detection, 3D reconstruction, Camera calibration)Technologies used: C++, ROS, OpenCV, Eigen, Conan, CMake, Jenkins, git
- 08.2015–06.2018 **Zürich, Switzerland**, *Accelerom AG, Software Engineer & System Administrator*, 20%-30%  
Accomplished tasks:
  - Extended and modified a Web-Tool
  - Administration of the Linux Server ArchitectureTechnologies used: Java, Groovy, JavaScript, jQuery, CSS, Grails, Hibernate, MySQL, git, Redmine, Tomcat, Apache, SAMBA

- 02.2014–08.2015 **Zürich, Switzerland**, *Laboratory for Orthopaedic Biomechanics at the University and ETH Zurich, Research Assistant*, 100%  
 Accomplished tasks:
  - Developed and implemented a new stretcher system
  - Extended and adapted a microscope control software
 Technologies used: C++, Qt, wxWidgets, CMake, git
- 11.2013–02.2014 **Zürich, Switzerland**, *Computer Assisted Research and Development, University Hospital Balgrist, Research Assistant (Civil service)*, 100%  
 Accomplished tasks:
  - Implementation of segmentation algorithms
  - Implementation of new features in existing software
 Technologies used: Matlab, C#, VTK, CVS
- 08.2013–11.2013 **Zürich, Switzerland**, *Laboratory for Orthopaedic Biomechanics at the University and ETH Zurich, Research Assistant (Civil service)*, 100%  
 Accomplished tasks:
  - Extended and adapted a microscope control software
  - Developed and implemented a stretcher control software
 Technologies used: C++, Qt, wxWidgets, CMake, git
- 08.2008–03.2009 **Wallisellen, Switzerland**, *ERPsourcing AG, Computer Science (Internship)*, 100%  
 Accomplished tasks:
  - Install and maintain new hardware
  - Install, repair and maintain Notebooks, Windows Workstations and Server
  - First and second level support for Microsoft Windows XP, Microsoft Vista and Microsoft Office
  - Install and maintain printer and print server
  - Customer support
- 08.2004–08.2008 **Rüti ZH, Switzerland**, *Hch. Kündig & Cie. AG, Electronics engineer (Apprenticeship)*, 100%  
 Accomplished tasks:
  - Creating Schema and Layout for PCB's
  - Programming Software in C for Micro Controller with RS and CAN Systems
  - Repair of PCB's
  - Creating documentations for the production
 Technologies used: Assembler, C, Micro controller, OrCAD, Altium Designer, Eagle

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## Publications

- 2021 Horvath, Aron et al. (Jan. 2021). “Focus on time: dynamic imaging reveals stretch-dependent cell relaxation and nuclear deformation”. In: *Biophysical Journal*. DOI: 10.1016/j.bpj.2021.01.020.
- 2019 Cieslewski, Titus, Andreas Ziegler, and Davide Scaramuzza (Oct. 2019). “Exploration Without Global Consistency Using Local Volume Consolidation”. In: *IFRR International Symposium on Robotics Research (ISRR), Hanoi, 2019*. IFRR: IEEE. URL: <https://doi.org/10.5167/uzh-197724>.

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## Languages

- German Mother tongue  
 English Excellent, Level C1  
 French Good, Level B1,  
 Chinese Basics, Level A2

Korean Basics, Level A2

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## Technical skills

Languages C++, Python, Julia, C, Java, C#, JavaScript, MATLAB, Assembler  
Software packages boost, ROS1/2, DDS, OpenCV, pcl, Eigen, scikit-learn, wxWidgets, Qt, MATLAB  
Infrastructure Microsoft Windows, Mac OS X, Linux, Apache, Tomcat, SAMBA  
Office Microsoft Office Package, LibreOffice Package, L<sup>A</sup>T<sub>E</sub>X, Markdown

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## Hobbies

Mountaineering Sportclimbing, Mountain tours, Skiing, Snowboarding, Skitouring  
Other sports Yoga, Kung Fu  
Music Drums, Piano, Vocals

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## Extra-Curricular activities

- Board member \*jev (Junge Evangelische Volkspartei Schweiz)
- Foodsaver at Foodsharing
- Managing a Labdoo acceptance point